

## Astronomical Image Processing

- Data/Image Processing:  
a raw image → calibrated image
- Data analysis
- Data reduction → calibrated data product



## Photometric Accuracy

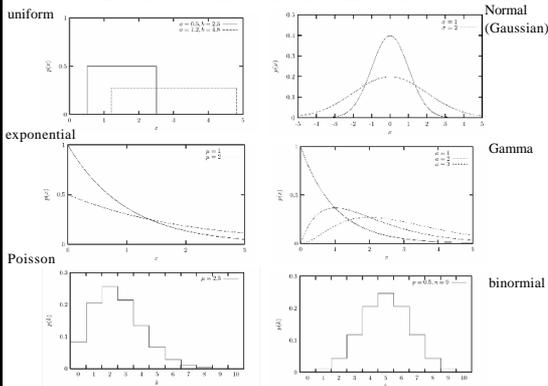
- What we measure  
= star ( $S$ ) + (sky) background ( $B$ ) + noise ( $N$ )
- What determines the faintest object detectable?  
 $S > B$ ?

**No!**

It is the  $S/N$  that determines the photometric accuracy and the detectability of the faintest object (the detecting limit)

e.g.,  $S/N \sim 3$ , a 3-sigma detection, would be a rather secured detection

## Distributions of Random Values



## Poisson Distribution (1/4)

most commonly used to model the number of random occurrences of some phenomenon in a specified unit of space or time

For example

1. number of phone calls received by a telephone operator in a 10-minute period
2. number of flaws in a bolt of fabric
3. number of typos per page made by a secretary

<http://stat.tamu.edu/stat30x/notes/node70.html>

## Poisson Distribution (2/4)

- For a Poisson random variable, the probability that  $X$  is some value  $x$  is given by the formula

$$P(X = x) = \frac{m^x e^{-m}}{x!}$$

where  $\mu$  is the average number of occurrences in the specified interval.

- For the Poisson distribution,

$$E(X) = m, \quad \text{Var}(X) = m$$

- That is, SD = uncertainty = SQRT(total events)

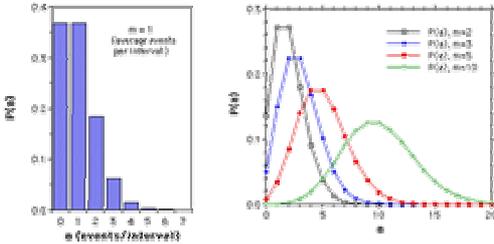
## Poisson Distribution (3/4)

- EXAMPLE 1: The number of false fire alarms in a suburb of Taipei averages 2.1 per day. Assuming that a Poisson distribution is appropriate, the probability that 4 false alarms will occur on a given day is given by

$$P(X = 4) = 2.1^4 e^{-2.1} / 4! = 0.0992$$

## Poisson Distribution (4/4)

Fifty dots distributed randomly over 50 scale divisions;  $m = 1$



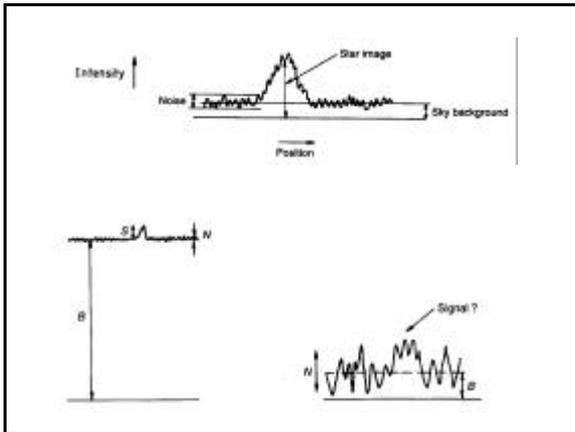
<http://info.bio.cmu.edu/Courses/03438/PBC97Poisson/PoissonPage.html#Features>

## Poisson Distribution --- Example

The spatial distribution of craters in a particular region of the moon has a Poisson distribution with average occurrence of 900 craters per square kilometer. NASA is planning a moon landing in the region and wants to know the probability that there are no craters within a circle of 50 meters in diameter from a preselected point in the region. What diameter circle will guarantee no craters inside with probability 0.9?

For the solution, see

<http://amath.colorado.edu/courses/4570/2003fall/SEC001002/q5solutions.pdf>



## Signal-to-Noise Ratio (S/N; SNR)

- For a random Poisson noise

$$N \sim \text{SQRT}(S)$$

$$\text{so } S/N = S / \text{SQRT}(S) = \text{SQRT}(S) \sim \text{SQRT}(t)$$

*S/N increases as the square-root of the integration time.*

More appropriate figure of merit for a detector

→ Detective Quantum Efficiency (DQE)

$$DQE = [(S/N)_{out} / (S/N)_{in}]^2$$

## Educated guess

A railroad company numbers its locomotives in order, 1, 2, ... N.

- One day, you see a locomotive, and its number is 60. What is your best guess for the total number N of locomotives which the company owns?
- On the following days, you see four more locomotives, all with numbers smaller than 60. What is your best guess for N based on this additional information?

Describe your reasoning carefully and in detail.

## Effects of Sky Background

- Scattered moonlight or sunlight

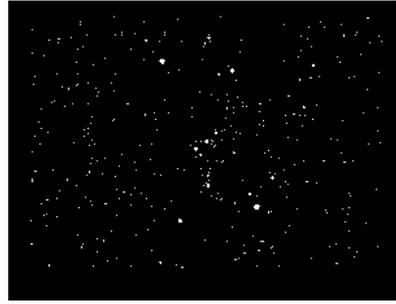
When the moon is up, i.e., a week around Full Moon, the sky is very bright and accurate photometry is not possible.

Radio observations, and some infrared observations, are possible during the day.

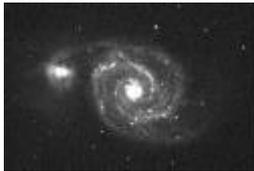


- +7.0 mag sky → a total of 14,000 stars, so a person in a perfect site can see ~7,000 stars
- +6.0 mag sky → ~2,400 stars visible
- +5.0 mag sky → ~800 stars visible, Milky Way barely visible
- +4.0 mag sky → < 250 stars visible, Milky Way not visible
- +3.0 mag sky → < 50 stars (typical in a city)
- +2.0 mag sky → < 25 stars (center of a big city)

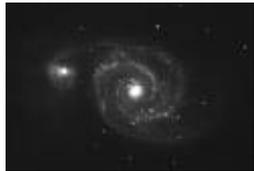
## Orion Constellation from +7.0 to 2.0 mag sky



<http://www.darksky.org/infoshts/is120.html>



A single exposure of the Whirlpool Galaxy



a median combine of three images

## Antiblooming

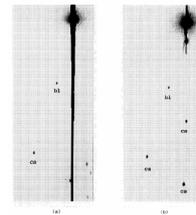
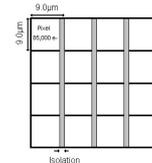
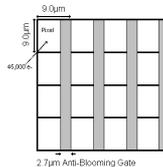


FIG. 1—800× exposures of RR Lyr PK3 0213-015 (M1, (a) normal exposure, (b) exposure with anti-blooming at 100 Hz clocking rate. The comparison star for the images has now appeared from behind the blooming. The light star is SAO 132656.



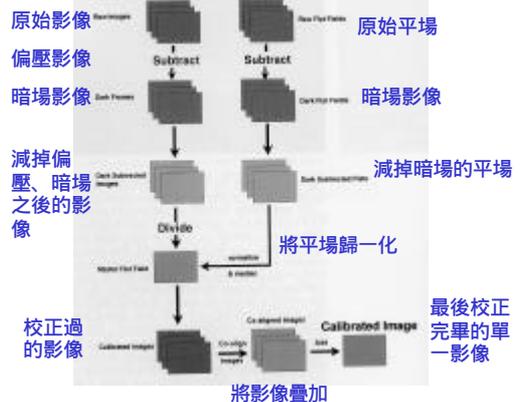
**No Anti-Blooming Gate**  
 100% Fill Factor  
 85,000 electron well depth  
 Higher Quantum Efficiency  
 Blooming (Breaking) possible



**Anti-Blooming Gate**  
 70% Fill Factor  
 45,000 electron well depth  
 Lower Quantum Efficiency

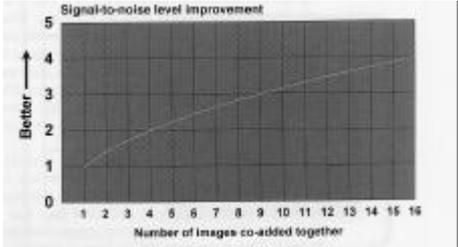
→ Loss of sensitivity

- **Bias frame** --- an exposure of zero time with the CCD covered, i.e., with the shutter closed. It is an image of the electronic noise present in the camera
- **Dark frame** --- an image produced by covering the CCD and taking a blank exposure. The exposure time is normally of the same duration as that of the target frame.
- **Flat field** --- an image of a totally uniform object such as a white screen. Used to correct the image for non-uniformity caused by the CCD itself and the optics.



# Noises

- **Photon (shot) noise** --- light arrives as discrete photon events → fluctuations in arrival rates
- **Thermal (Johnson or Nyquist) noise** --- generated in all resistors, from random nature of the motion of the charge carriers
- **Readout noise** --- errors introduced by stray capacitance in the (CCD) readout circuit  
 →  $S^2_{total} = S_i S^2_i$



# Arts of Imaging Processing

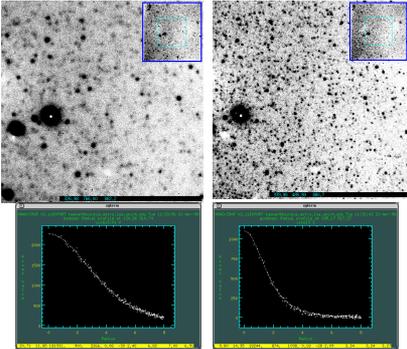
Q: What can go wrong with CCD imaging?

A: Everything!

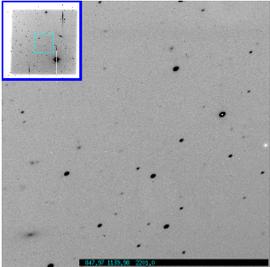
- seeing, focusing, guiding
- cosmic rays
- fringing
- dust rings
- reflections
- diffraction spikes

[http://www.ciw.edu/vonbraun/obs\\_mishaps/mishaps.html](http://www.ciw.edu/vonbraun/obs_mishaps/mishaps.html)

- **Effects of Bad Seeing** Stellar images spread out uniformly, without elongation

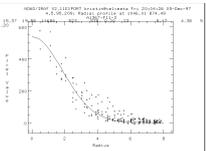


- **Effects of Bad Focus** Stellar images elongated in direction of astigmatism on some part of the frame

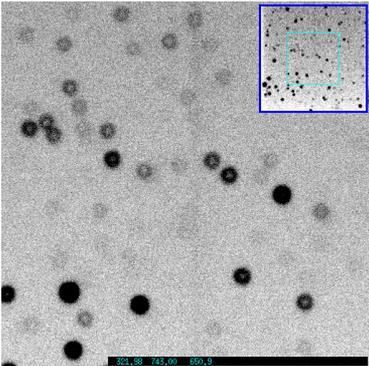


If elongation EW or NS → bad guiding?

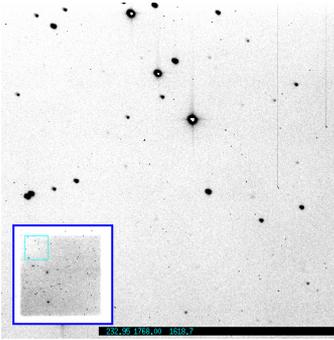
If elongation in all parts of image → bad focusing?



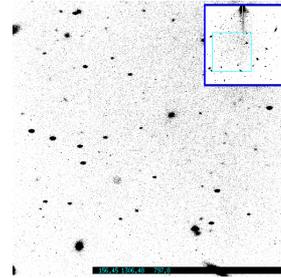
If way out of focus → donut shape



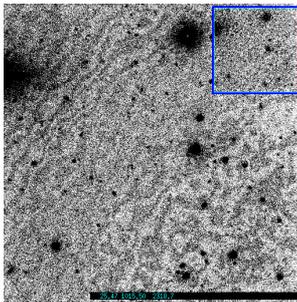
Effect of coma



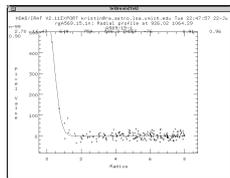
- **Effects of Bad Guiding** Stellar images elongated in NS or EW uniformly in the frame



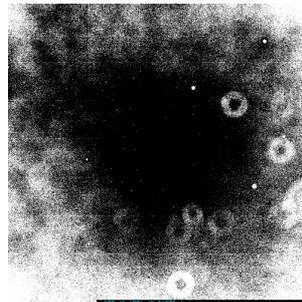
- **Interference fringes** due to (multiple) internal reflections



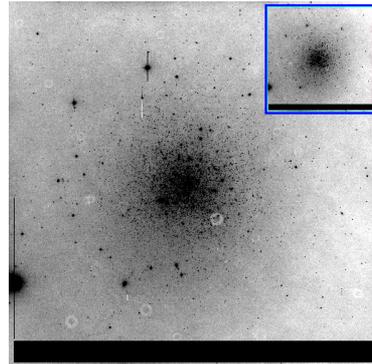
cosmic ray: point-like  
star: Gaussian



- **Dust rings** caused by dust on dewar window or filters; show up in all frames

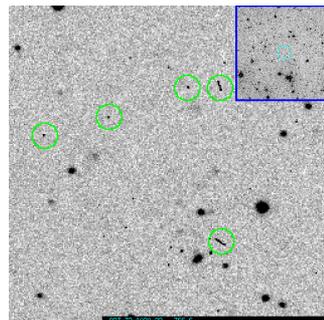


Dewar window dust → stationary  
Filter dust → moved throughout run (and even in a night) → evening and dawn flats

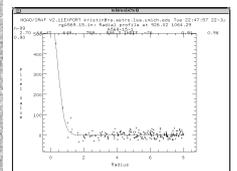


Dust ring and readout error

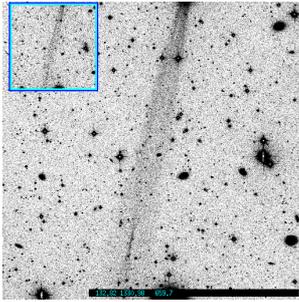
- **Cosmic rays** streaks and dots caused by energetic particles striking the CCD



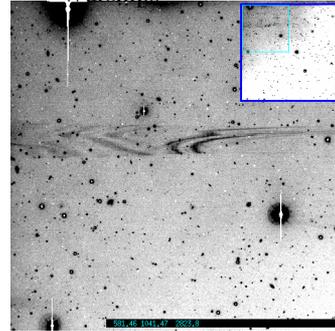
cosmic ray → point-like  
Star → Gaussian



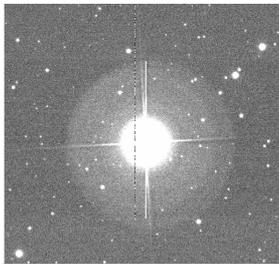
- **Reflection** caused by reflection or scattering off some part of the telescope (or dome)



“Romulan Warships”

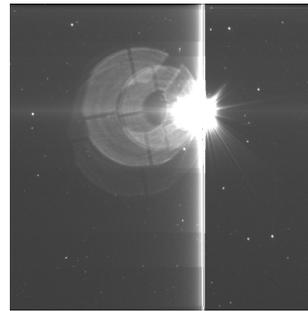


- **Diffraction spikes** caused by (the Fourier Transform of) the support struts which hold the secondary mirror in place.



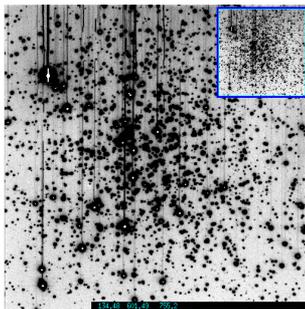
**Internal reflection**  
Part of the light hitting the CCD surface is reflected back toward the dewar window and the filter, then reflected back toward the CCD surface where it is perceived as out of focus (thus the doughnuts).

Circularly symmetric in this case



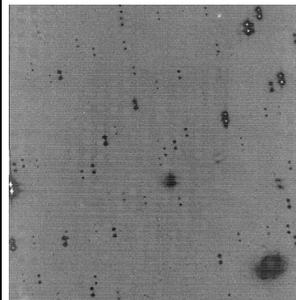
Reflecting surface or the CCD is tilted.  
“Hole” in the center of each donut → alignment ok!

**Q: What could this be caused by?**



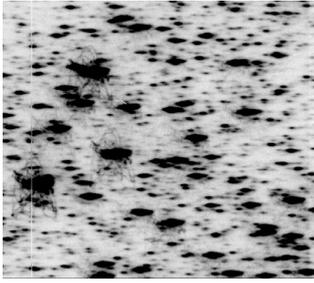
**A:** Shutter failure ..... bright trails of stars caused by the fact that the shutter was not closed when the CCD was read out.

**Q: What could this be caused by?**



**A:** guider jumped

Q: What could this be caused by?



A: An earthquake!